

Extremos Locales parte 2

Para el caso de funciones $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ tenemos que recordando un poco de la expresión de Taylor

$$f(x, y) = f(x_0, y_0) + \left(\frac{\partial f}{\partial x}\right)_p (x - x_0) + \left(\frac{\partial f}{\partial y}\right)_p (y - y_0) + \left(\frac{\partial f}{\partial z}\right)_p (z - z_0) +$$

$$\frac{1}{2!} \left(\frac{\partial^2 f}{\partial x^2} (x - x_0)^2 + 2 \frac{\partial^2 f}{\partial x \partial y} (x - x_0)(y - y_0) + \frac{\partial^2 f}{\partial y^2} (y - y_0)^2 + 2 \frac{\partial^2 f}{\partial x \partial z} (z - z_0)(x - x_0) + 2 \frac{\partial^2 f}{\partial y \partial z} (z - z_0)(y - y_0) \right)$$

$$+ \frac{\partial^2 f}{\partial z^2} (z - z_0)$$

Haciendo $x - x_0 = h_1$, $y - y_0 = h_2$, $z - z_0 = h_3$ podemos escribir el término rojo de la siguiente manera

$$\frac{1}{2!} \left(\frac{\partial^2 f}{\partial x^2} h_1^2 + 2 \frac{\partial^2 f}{\partial x \partial y} h_1 h_2 + \frac{\partial^2 f}{\partial y^2} h_2^2 + 2 \frac{\partial^2 f}{\partial x \partial z} h_3 h_1 + 2 \frac{\partial^2 f}{\partial y \partial z} h_3 h_2 + \frac{\partial^2 f}{\partial z^2} h_3^2 \right)$$

y también se puede ver como producto de matrices

$$\frac{1}{2!} (h_1 \ h_2 \ h_3) \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial z \partial x} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial z \partial y} \\ \frac{\partial^2 f}{\partial x \partial z} & \frac{\partial^2 f}{\partial y \partial z} & \frac{\partial^2 f}{\partial z^2} \end{pmatrix}_p \begin{pmatrix} h_1 \\ h_2 \\ h_3 \end{pmatrix}$$

Si (x_0, y_0, z_0) es un punto crítico de la función entonces en la expresión de Taylor

$$f(x, y) = f(x_0, y_0) + \left(\frac{\partial f}{\partial x}\right)_p (x - x_0) + \left(\frac{\partial f}{\partial y}\right)_p (y - y_0) + \left(\frac{\partial f}{\partial z}\right)_p (z - z_0)$$

$$\frac{1}{2!} \left(\frac{\partial^2 f}{\partial x^2} (x - x_0)^2 + 2 \frac{\partial^2 f}{\partial x \partial y} (x - x_0)(y - y_0) + \frac{\partial^2 f}{\partial y^2} (y - y_0)^2 + 2 \frac{\partial^2 f}{\partial x \partial z} (z - z_0)(x - x_0) + 2 \frac{\partial^2 f}{\partial y \partial z} (z - z_0)(y - y_0) \right)$$

$$+ \frac{\partial^2 f}{\partial z^2} (z - z_0)(x - x_0)$$

El término

$$\frac{\partial f}{\partial x}_p (x - x_0) + \frac{\partial f}{\partial y}_p (y - y_0) + \frac{\partial f}{\partial z}_p (z - z_0) = 0$$

y por lo tanto

$$f(x, y) - f(x_0, y_0) = \frac{1}{2!} (h_1 \ h_2 \ h_3) \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial z \partial x} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial z \partial y} \\ \frac{\partial^2 f}{\partial x \partial z} & \frac{\partial^2 f}{\partial y \partial z} & \frac{\partial^2 f}{\partial z^2} \end{pmatrix}_p \begin{pmatrix} h_1 \\ h_2 \\ h_3 \end{pmatrix}$$

vamos a determinar el signo de la forma

$$Q(h) = \frac{1}{2!} (h_1 \ h_2 \ h_3) \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial z \partial x} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial z \partial y} \\ \frac{\partial^2 f}{\partial x \partial z} & \frac{\partial^2 f}{\partial y \partial z} & \frac{\partial^2 f}{\partial z^2} \end{pmatrix}_p \begin{pmatrix} h_1 \\ h_2 \\ h_3 \end{pmatrix}$$



vamos a trabajar sin el término $\frac{1}{2!}$ que no afectara al signo de la expresión, tenemos entonces

$$Q(h) = (h_1 \ h_2 \ h_3) \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial z \partial x} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial z \partial y} \\ \frac{\partial^2 f}{\partial x \partial z} & \frac{\partial^2 f}{\partial y \partial z} & \frac{\partial^2 f}{\partial z^2} \end{pmatrix} \begin{pmatrix} h_1 \\ h_2 \\ h_3 \end{pmatrix} = \frac{\partial^2 f}{\partial x^2} h_1^2 + 2 \frac{\partial^2 f}{\partial x \partial y} h_1 h_2 + \frac{\partial^2 f}{\partial y^2} h_2^2 + 2 \frac{\partial^2 f}{\partial x \partial z} h_3 h_1 + 2 \frac{\partial^2 f}{\partial y \partial z} h_3 h_2 + \frac{\partial^2 f}{\partial z^2} h_3^2$$

$$= \frac{\partial^2 f}{\partial x^2} \left(h_1 + \frac{\frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}} h_2 \right)^2 + \left(\frac{\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2}{\frac{\partial^2 f}{\partial x^2}} \right) h_2^2 + 2 \frac{\partial^2 f}{\partial x \partial z} h_3 h_1 + 2 \frac{\partial^2 f}{\partial y \partial z} h_3 h_2 + \frac{\partial^2 f}{\partial z^2} h_3^2$$

hacemos $b_1 = \frac{\partial^2 f}{\partial x^2}$, $h'_1 = \left(h_1 + \frac{\frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}} h_2 \right)$, $b_2 = \frac{\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2}{\frac{\partial^2 f}{\partial x^2}}$, $h'_2 = h_2$ y obtenemos

$$= b_1 h_1'^2 + b_2 h_2'^2 + 2 \frac{\partial^2 f}{\partial x \partial z} h_3 h_1 + 2 \frac{\partial^2 f}{\partial y \partial z} h_3 h_2 + \frac{\partial^2 f}{\partial z^2} h_3^2$$

que podemos escribir

$$= b_1 h_1'^2 + b_2 h_2'^2 + 2 \frac{\partial^2 f}{\partial x \partial z} \left(h_1 + \frac{\frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}} h_2 - \frac{\frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}} h_2 \right) h_3 + 2 \frac{\partial^2 f}{\partial y \partial z} h_3 h_2 + \frac{\partial^2 f}{\partial z^2} h_3^2$$

$$= b_1 h_1'^2 + b_2 h_2'^2 + 2 \frac{\partial^2 f}{\partial x \partial z} \left(h'_1 - \frac{\frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}} h'_2 \right) h_3 + 2 \frac{\partial^2 f}{\partial y \partial z} h_3 h_2 + \frac{\partial^2 f}{\partial z^2} h_3^2$$

$$= b_1 h_1'^2 + b_2 h_2'^2 + 2 \frac{\partial^2 f}{\partial x \partial z} h'_1 h_3 + \left(2 \frac{\partial^2 f}{\partial y \partial z} - \frac{2 \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}} \right) h'_2 h_3 + \frac{\partial^2 f}{\partial z^2} h_3^2$$

hacemos

$$2b_{23} = 2 \frac{\partial^2 f}{\partial y \partial z} - \frac{2 \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}}$$

y obtenemos

$$= b_1 h_1'^2 + b_2 h_2'^2 + 2 \frac{\partial^2 f}{\partial x \partial z} h'_1 h_3 + 2b_{23} h'_2 h_3 + \frac{\partial^2 f}{\partial z^2} h_3^2$$

que se puede escribir

$$= b_1 \left(h_1'^2 + 2 \frac{\frac{\partial^2 f}{\partial x \partial z}}{b_1} h'_1 h_3 + \left(\frac{\frac{\partial^2 f}{\partial x \partial z} h_3}{b_1} \right)^2 \right) + b_2 \left(h_2'^2 + 2 \frac{b_{23}}{b_2} h'_2 h_3 + \left(\frac{b_{23}}{b_2} h_3 \right)^2 \right) + \left(\frac{\partial^2 f}{\partial z^2} - \frac{\left(\frac{\partial^2 f}{\partial x \partial z} \right)^2}{b_1} - \frac{b_{23}^2}{b_2} \right) h_3^2$$

hacemos

$$b_3 = \frac{\partial^2 f}{\partial z^2} - \frac{\left(\frac{\partial^2 f}{\partial x \partial z} \right)^2}{b_1} - \frac{b_{23}^2}{b_2}$$



y obtenemos

$$\begin{aligned}
 &= b_1 \left(h_1'^2 + 2 \frac{\partial^2 f}{\partial x \partial z} h_1' h_3 + \left(\frac{\partial^2 f}{\partial x \partial z} h_3 \right)^2 \right) + b_2 \left(h_2'^2 + 2 \frac{b_{23}}{b_2} h_2' h_3 + \left(\frac{b_{23}}{b_2} h_3 \right)^2 \right) + b_3 h_3^2 \\
 &= b_1 \left(h_1' + \frac{\partial^2 f}{\partial x \partial z} h_3 \right)^2 + b_2 \left(h_2' + \frac{b_{23}}{b_2} h_3 \right)^2 + b_3 h_3^2
 \end{aligned}$$

esta última expresión será positiva si y solo si $b_1 > 0$, $b_2 > 0$ y $b_3 > 0$ en clases pasadas vimos los dos primeros, veamos ahora que

$$b_3 = \frac{\partial^2 f}{\partial z^2} - \frac{\left(\frac{\partial^2 f}{\partial x \partial z} \right)^2}{b_1} - \frac{b_{23}^2}{b_2} > 0$$

tenemos entonces que

$$\begin{aligned}
 &\frac{\partial^2 f}{\partial z^2} - \frac{\left(\frac{\partial^2 f}{\partial x \partial z} \right)^2}{b_1} - \frac{b_{23}^2}{b_2} = \frac{\partial^2 f}{\partial z^2} - \frac{\left(\frac{\partial^2 f}{\partial x \partial z} \right)^2}{\frac{\partial^2 f}{\partial z^2}} - \frac{\left(\frac{\partial^2 f}{\partial y \partial z} - \frac{2 \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial x^2}} \right)^2}{\frac{\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2}} \\
 &= \frac{\frac{\partial^2 f}{\partial z^2} \frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial x \partial z} \right)^2}{\frac{\partial^2 f}{\partial x^2}} - \frac{\frac{\left(\frac{\partial^2 f}{\partial y \partial z} \frac{\partial^2 f}{\partial x^2} - \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x} \right)^2}{\left(\frac{\partial^2 f}{\partial x^2} \right)^2}}{\frac{\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2}} = \frac{\frac{\partial^2 f}{\partial z^2} \frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial x \partial z} \right)^2}{\frac{\partial^2 f}{\partial x^2}} - \frac{\left(\frac{\partial^2 f}{\partial y \partial z} \frac{\partial^2 f}{\partial x^2} - \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x} \right)^2}{\left(\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 \right) \frac{\partial^2 f}{\partial x^2}} \\
 &= \frac{\left(\frac{\partial^2 f}{\partial z^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial x \partial z} \right)^2 \right) \left(\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 \right) - \left(\frac{\partial^2 f}{\partial y \partial z} \frac{\partial^2 f}{\partial x^2} - \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x} \right)^2}{\frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 \right)} \\
 &= \frac{\frac{\partial^2 f}{\partial z^2} \frac{\partial^2 f}{\partial x^2} \frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \frac{\partial^2 f}{\partial z^2} \frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 - \frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial x \partial z} \right)^2 + \left(\frac{\partial^2 f}{\partial x \partial z} \right)^2 \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 - \left(\frac{\partial^2 f}{\partial y \partial z} \right)^2 \left(\frac{\partial^2 f}{\partial x^2} \right)^2 - \frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 \right)}{\frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 \right)} \\
 &= \frac{2 \left(\frac{\partial^2 f}{\partial x^2} \frac{\partial^2 f}{\partial y \partial z} \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x} \right) - \left(\frac{\partial^2 f}{\partial x \partial z} \right)^2 \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2}{\frac{\partial^2 f}{\partial x^2} \left(\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 \right)} \\
 &= \frac{\frac{\partial^2 f}{\partial z^2} \frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \frac{\partial^2 f}{\partial z^2} \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2 - \frac{\partial^2 f}{\partial y^2} \left(\frac{\partial^2 f}{\partial x \partial z} \right)^2 - \left(\frac{\partial^2 f}{\partial y \partial z} \right)^2 \frac{\partial^2 f}{\partial x^2} + 2 \frac{\partial^2 f}{\partial y \partial z} \frac{\partial^2 f}{\partial x \partial z} \frac{\partial^2 f}{\partial y \partial x}}{\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2}
 \end{aligned}$$



$$= \frac{\begin{vmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial z \partial x} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial z \partial y} \\ \frac{\partial^2 f}{\partial x \partial z} & \frac{\partial^2 f}{\partial y \partial z} & \frac{\partial^2 f}{\partial z^2} \end{vmatrix}}{\frac{\partial^2 f}{\partial y^2} \frac{\partial^2 f}{\partial x^2} - \left(\frac{\partial^2 f}{\partial y \partial x} \right)^2}$$

por lo tanto

$$b_3 > 0 \Leftrightarrow \begin{vmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial z \partial x} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial z \partial y} \\ \frac{\partial^2 f}{\partial x \partial z} & \frac{\partial^2 f}{\partial y \partial z} & \frac{\partial^2 f}{\partial z^2} \end{vmatrix} > 0$$

Definición 1. La forma $Q(x) = xAx^t$, que tiene asociada la matriz A (respecto a la base canónica de \mathbb{R}^n) se dice:

Definida positiva, si $Q(x) > 0 \quad \forall x \in \mathbb{R}^n$

La forma $Q(x) = xAx^t$, que tiene asociada la matriz A (respecto a la base canónica de \mathbb{R}^n) se dice:

Definida negativa, si $Q(x) < 0 \quad \forall x \in \mathbb{R}^n$

Definición 2. Si la forma $Q(x) = xAx^t$ es definida positiva, entonces f tiene un mínimo local en x . Si la forma $Q(x) = xAx^t$ es definida negativa, entonces f tiene un máximo local en x .

Hay criterios similares para una matriz simétrica A de $n \times n$ y consideramos las n submatrices cuadradas a lo largo de la diagonal, A es definida positiva si y solo si los determinantes de estas submatrices diagonales son todos mayores que cero. Para A definida negativa los signos deberán alternarse < 0 y > 0 . En casi de que los determinantes de las submatrices diagonales sean todos diferentes de cero pero que la matrix no sea definida positiva o negativa, el punto crítico es tipo silla. Y por lo tanto el punto no es máximo ni mínimo. Así tenemos el siguiente resultado.

$$\left[\begin{array}{c} \left[\begin{array}{c} [] \\ [] \\ [] \\ [] \end{array} \right] \\ \left[\begin{array}{c} [] \\ [] \\ [] \end{array} \right] \\ \left[\begin{array}{c} [] \\ [] \end{array} \right] \\ \left[\begin{array}{c} [] \end{array} \right] \end{array} \right]$$

Definición 3. Dada una matriz cuadrada $A = a_{ij} \quad j = 1, \dots, n \quad i = 1, \dots, n$ se consideran las submatrices angulares $A_k \quad k = 1, \dots, n$ definidas como

$$A_1 = (a_{11}) \quad A_2 = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad A_3 = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}, \dots, A_n = A$$

se define $\det A_k = \Delta_k$

Definición 4. Se tiene entonces que que la forma $Q(x) = xAX^t$ es definida positiva si y solo si todos los dterminantes $\Delta_k \quad k = 1, \dots, n$ son números positivos



Definición 5. La forma $Q(x) = xAX^t$ es definida negativa si y solo si los determinantes Δ_k $k = 1, \dots, n$ tienen signos alternados comenzando por $\Delta_1 < 0$, $\Delta_2 > 0$, ... respectivamente

Ejemplo: Consideremos la función $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ $f(x, y, z) = \sin x + \sin y + \sin z - \sin(x + y + z)$, el punto $P = (\frac{\pi}{2}, \frac{\pi}{2}, \frac{\pi}{2})$ es un punto crítico de f y en ese punto la matriz hessiana de f es

$$H(p) = \begin{bmatrix} -2 & -1 & -1 \\ -1 & -2 & -1 \\ -1 & -1 & -2 \end{bmatrix}$$

los determinantes de las submatrices angulares son

$$\Delta_1 = \det(-2)$$

$$\Delta_2 = \det \begin{bmatrix} -2 & -1 \\ -1 & -2 \end{bmatrix}$$

$$\Delta_3 = \det H(p) = -4$$

puesto que son signos alternantes con $\Delta_1 < 0$ concluimos que la función f tiene en $(\frac{\pi}{2}, \frac{\pi}{2}, \frac{\pi}{2})$ un máximo local. Este máximo local vale $f(\frac{\pi}{2}, \frac{\pi}{2}, \frac{\pi}{2}) = 4$

